



Top-side unit

Transducer

Screenshot of the operating software

► Performance

- water depth range: 0.5 – 400 m
- penetration: up to 40 m, depending on sediments
- layer resolution: up to 5 cm
- motion compensation: heave
- beam width @ 3 dB:  $\pm 2^\circ$  / footprint < 7 % of water depth for all frequencies

► Transmitter

- primary frequencies: approx. 100 kHz (band 85 – 115 kHz)
- secondary low frequencies: 4, 5, 6, 8, 10, 12, 15 kHz (band 2 – 22 kHz)
- primary source level: > 238 dB/ $\mu$ Pa re 1 m
- pulse width: 0.07 – 1 ms
- pulse rate: up to 50/s
- multi-ping mode
- pulse type: CW, Ricker

► Acquisition

- primary frequency (echo sounder, bottom track)
- secondary low frequency (sub-bottom data, multi-frequency mode)
- sample rate 96 kHz @ 24 bit

► System Components

- transceiver unit 19 inch / 7 U (WHD: 0.52 m x 0.35 m x 0.40 m; 31 kg)
- transducer incl. 20 m cable (WHD: 0.34 m x 0.08 m x 0.26 m; 22 kg)
- system control: internal PC

# SES-2000 light

## Parametric Sub-bottom Profiler

► Software

- SESWIN data acquisition software
- SES Convert SEG-Y/XTF data export
- SES NetView remote display
- ISE post-processing software

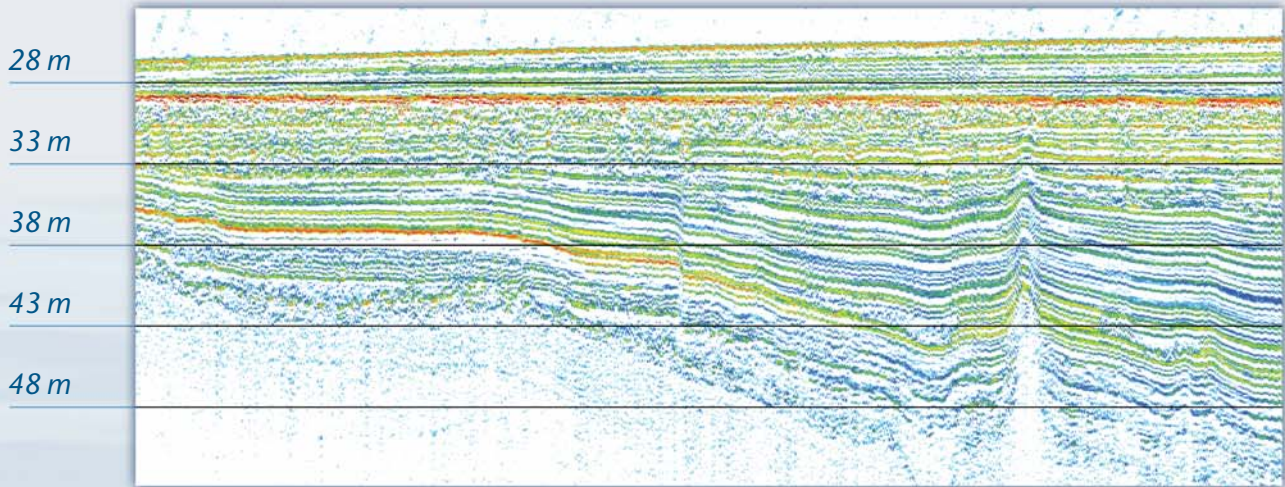
► Power Supply Requirements

- 100 – 240 V AC / 50 – 60 Hz
- power consumption: < 250 W

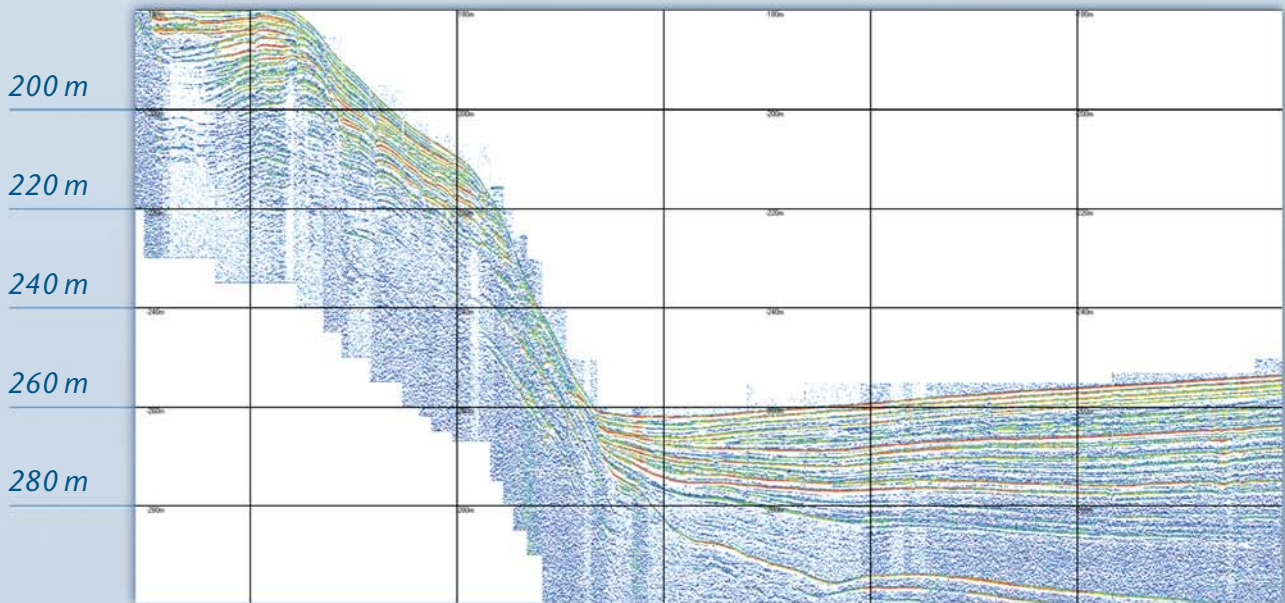


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# Survey examples of SES-2000 light



*Baltic Sea echo plot example – Frequency 8 kHz, pulse length 375  $\mu$ s, profile length 4000 m*



*Lake Ohrid (Macedonia) echo plot example – Frequency 10 kHz, pulse length 500  $\mu$ s, profile length 5500 m*

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